Software Modelling design report

For the existing model. In order to make it a new function that can bring robots together and start carrying a heavy item, and in the existing model, it’s the job of the mailpool that assign the mail item to the robots’ hands and tube, then the robots can start carrying the mail item and deliver them. So, we come up an idea that to do something d­ifferent with the mailpool so it will assign the heavy item to a group of robots.

There is a IMailPool.java with is an interface that for the mailpool, so we were thinking to use it to construct a new class that can assign for heavy item which implement IMailPool, called it WeightDistributeMailPool. But after we started to code and realize that, the WeightDistributeMailPool is actually behavior quite similar to the mailpool with only adding a new functionality for the heavy item. In the thought of that, we use the Polymorphism to reduce writing duplicated code. We used the existing MailPool class as a base and the WeightDistributeMailPool to inheritance it, and we override the void step() function which is the function to do the job of distribution.

And we have notices that the mailpool might be doing too many jobs as it not only added mail to itself, and it also do the job of distribute the mail to the robots. So we decide to separate the distribution job from the mail pool, and assign it to a distribution system, to make it has a higher cohesion. The mailpool now has a more focus job and it’s easy to change if one day that people decide that using the same mail pool but distribute the mail in a different way. They only need to change the distributing system, instead of the whole mailpool. So we create a new interface called IdistributeSystem, with only a single function distribute(). And then the in the step() function of both mailpool, we change the step() function with only a distributeSystem.distribute() inside.

In the WeightDistributeSystem.java, when we were writing the function to load the item to the robot, we created a helper class with all the static method to help loading. Therefore if in the future, if people want to make a more complicated distributeSystem and it including weight, they can use the method straight away from the helper class without creating any extra objects.

After taking care of the distribution of the heavy mail item, we need to notify the robots that they are now on a team as according to the requirement, the robots that moving in team, will be 1/3 times in the movement speed. First we notice that, the robot start moving a function in the Robot class called dispatch(), which is weird that as the robot is the one get dispatched, instead of dispatch someone. And since now we have a distributeSystem, it makes more sense that the system do the dispatch job as it might be a different way to dispatch the robot. In this way, we make a higher cohesion for both the robot and the distributeSystem as they now are more focusing on their own job.

As in the movement speed for the team, the easiest way is just added a variable to the robot class to tell if the robot in a team and then control it’s movement by that. However, this will introduce more variable and a lot of messy function in the class and not extendable. So we using the indirection pattern, create a new interface called behavior, and the distributeSystem dispatch the robot to control the behavior of the robot, and the moveforward() function of the robot is now moved to the interface as they in different behavior, the movement will be different. There are only 2 different behavior in the scenario: TeamBehaviour and SoloBehaviour. But people can added more in the future as it’s a interface.

During the process of using indirection pattern with the Interface Behaviour. We need some information about the robot, in order to control its movement. So, we create an Information expert for the Robot, called Info, to record some information of the robot and then share to the Behaviour to use it.

After taking care of both distribution and the robot behavior. We need to take care of the Delivery, according to the original model, if we have a team of three robots to deliver the mail, it will produce the exception that said the mail is already deliver.